Carnegie Mellon University

99 Index Concurrency





ADMINISTRIVIA

Project #1 is due Fri Sept 27th @ 11:59pm

Homework #2 is due Mon Sept 30th @ 11:59pm

Project #2 will be released Mon Sept 30th



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OBSERVATION

We assumed that all the data structures that we have discussed so far are single-threaded.

But we need to allow multiple threads to safely access our data structures to take advantage of additional CPU cores and hide disk I/O stalls.



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CONCURRENCY CONTROL

A <u>concurrency control</u> protocol is the method that the DBMS uses to ensure "correct" results for concurrent operations on a shared object.

- A protocol's correctness criteria can vary:
- → **Logical Correctness:** Can I see the data that I am supposed to see?
- → **Physical Correctness:** Is the internal representation of the object sound?



TODAY'S AGENDA

Latches Overview Hash Table Latching B+Tree Latching Leaf Node Scans Delayed Parent Updates





LOCKS VS. LATCHES

Locks

- \rightarrow Protects the database's logical contents from other txns.
- \rightarrow Held for txn duration.
- \rightarrow Need to be able to rollback changes.

Latches

- \rightarrow Protects the critical sections of the DBMS's internal data structure from other threads.
- \rightarrow Held for operation duration.
- \rightarrow Do not need to be able to rollback changes.

LOCKS VS. LATCHES

Lecture 17	Locks	Latches
Separate	User transactions	Threads
Protect	Database Contents	In-Memory Data Structures
During	Entire Transactions	Critical Sections
Modes	Shared, Exclusive, Update, Intention	Read, Write
Deadlock	Detection & Resolution	Avoidance
by	Waits-for, Timeout, Aborts	Coding Discipline
Kept in	Lock Manager	Protected Data Structure
Source: <u>Goetz Graefe</u>		

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LATCH MODES

Read Mode

- \rightarrow Multiple threads can read the same object at the same time.
- \rightarrow A thread can acquire the read latch if another thread has it in read mode.

Write Mode

- \rightarrow Only one thread can access the object.
- \rightarrow A thread cannot acquire a write latch if another thread holds the latch in any mode.





Approach #1: Blocking OS Mutex

- \rightarrow Simple to use
- \rightarrow Non-scalable (about 25ns per lock/unlock invocation)
- \rightarrow Example: **std::mutex**

```
std::mutex m;
i
m.lock();
// Do something special...
m.unlock();
```



Approach #2: Test-and-Set Spin Latch (TAS)

- \rightarrow Very efficient (single instruction to latch/unlatch)
- \rightarrow Non-scalable, not cache friendly
- \rightarrow Example: **std::atomic<T>**

```
std::atomic<bool>
std::atomic_flag latch;
.
```

```
while (latch.test_and_set(...)) {
    // Retry? Yield? Abort?
```



- \rightarrow Allows for concurrent readers
- \rightarrow Must manage read/write queues to avoid starvation
- \rightarrow Can be implemented on top of spinlocks



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HASH TABLE LATCHING

Easy to support concurrent access due to the limited ways threads access the data structure.

- \rightarrow All threads move in the same direction and only access a single page/slot at a time.
- \rightarrow Deadlocks are not possible.

To resize the table, take a global latch on the entire table (i.e., in the header page).



HASH TABLE LATCHING

Approach #1: Page Latches

- \rightarrow Each page has its own reader-write latch that protects its entire contents.
- \rightarrow Threads acquire either a read or write latch before they access a page.

Approach #2: Slot Latches

- \rightarrow Each slot has its own latch.
- \rightarrow Can use a single mode latch to reduce meta-data and computational overhead.





























T₁: Find D hash(D)



T₂: Insert E hash(E) 15

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HASH TABLE - SLOT LATCHES



B+TREE CONCURRENCY CONTROL

We want to allow multiple threads to read and update a B+Tree at the same time.

- We need to protect from two types of problems:
- \rightarrow Threads trying to modify the contents of a node at the same time.
- \rightarrow One thread traversing the tree while another thread splits/merges nodes.





















LATCH CRABBING/COUPLING

Protocol to allow multiple threads to access/modify B+Tree at the same time.

Basic Idea:

- \rightarrow Get latch for parent.
- \rightarrow Get latch for child
- \rightarrow Release latch for parent if "safe".

A <u>safe node</u> is one that will not split or merge when updated.

- \rightarrow Not full (on insertion)
- \rightarrow More than half-full (on deletion)



LATCH CRABBING/COUPLING

Find: Start at root and go down; repeatedly,

- \rightarrow Acquire **R** latch on child
- \rightarrow Then unlatch parent

Insert/Delete: Start at root and go down, obtaining **W** latches as needed. Once child is latched, check if it is safe:

 \rightarrow If child is safe, release all latches on ancestors.





















EXAMPLE #2 - DELETE 38





EXAMPLE #2 - DELETE 38



EXAMPLE #2 - DELETE 38


































OBSERVATION

What was the first step that all the update examples did on the B+Tree?





OBSERVATION

What was the first step that all the update examples did on the B+Tree?

Taking a write latch on the root every time becomes a bottleneck with higher concurrency.

Can we do better?



BETTER LATCHING ALGORITHM

Assume that the leaf node is safe.

Use read latches and crabbing to reach it, and then verify that it is safe.

If leaf is not safe, then do previous algorithm using write latches.

Acta Informatica 9, 1-21 (1977)



Concurrency of Operations on B-Trees

R. Bayer * and M. Schkolnick IBM Research Laboratory, San José, CA 95193, USA

> Summary, Concurrent operations on *B*-trees pose the problem of insuring that each operation can be carried of utilitation thereform, with other operations being performed simultaneously by other users. This problem can become critical if these structures are being used to support access paths, like indexes, to data base systems. In this case, serializing access to one of these indexes can create an unacceptable bottlemek for the entire system. Thus, there is a need for locking protocids that can assure integrity for each access while at the same time providing a maximum possible degree of concurrency. Another feature required from these protocols is that they be detallock free, isoche a deadlock may be high.

> Recently, there has been some questioning on whether B-tree structures can support concurrent operations. In this paper, we examine the problem of concurrent access to B-trees. We present a deadlock free solution which can be tuned to specific requirements. An analysis is presented which allows the selection of parameters so as to satisfy these requirements.

> The solution presented here uses simple locking protocols. Thus, we conclude that B-trees can be used advantageously in a multi-user environment.

1. Introduction

In this paper, we examine the problem of concurrent access to indexes which are maintained as H-resc. This type of organization was introduced by Bayer and McCreight [2] and some variants of it appear in Knuth [10] and Wedekind [13]. Performance studies of it were restricted to the single user environment. Recently, these structures have been examined for possible use in a multi-user (concurrent) environment. Some initial studies have been made about the feasibility of their use in this type of situation [1, 6], and [11].

An accessing schema which achieves a high degree of concurrency in using the index will be presented. The schema allows dynamic tuning to adapt its performance to the profile of the current set of users. Another property of the

 Permanent address: Institut f
ür Informatik der Technischen Universit
ät M
ünchen, Arcisstr. 21, D-8000 M
ünchen 2, Germany (Fed. Rep.)

















BETTER LATCHING ALGORITHM

Search: Same as before.

Insert/Delete:

- \rightarrow Set latches as if for search, get to leaf, and set W latch on leaf.
- → If leaf is not safe, release all latches, and restart thread using previous insert/delete protocol with write latches.

This approach optimistically assumes that only leaf node will be modified; if not, **R** latches set on the first pass to leaf are wasteful.



OBSERVATION

The threads in all the examples so far have acquired latches in a "top-down" manner.

- \rightarrow A thread can only acquire a latch from a node that is below its current node.
- \rightarrow If the desired latch is unavailable, the thread must wait until it becomes available.

But what if we want to move from one leaf node to another leaf node?





T_1 : Find Keys < 4





T_1 : Find Keys < 4







T_1 : Find Keys < 4





T_1 : Find Keys < 4





T₁: Find Keys < 4 **T**₂: Find Keys > 1









T₁: Find Keys < 4 **T**₂: Find Keys > 1







T₁: Find Keys < 4 **T**₂: Find Keys > 1















T₁: Delete 4 **T₂:** Find Keys > 1









LEAF NODE SCAN EXAMPLE #3 T₁: Delete 4 T_2 : Find Keys > 1 3 *T*₂ cannot acquire the read latch on *C* R W 3 2 B







LEAF NODE SCANS

Latches do <u>not</u> support deadlock detection or avoidance. The only way we can deal with this problem is through coding discipline.

The leaf node sibling latch acquisition protocol must support a "no-wait" mode.

The DBMS's data structures must cope with failed latch acquisitions.



DELAYED PARENT UPDATES

Every time a leaf node overflows, we must update at least three nodes.

- \rightarrow The leaf node being split.
- \rightarrow The new leaf node being created.
- \rightarrow The parent node.

B^{link}-**Tree Optimization:** When a leaf node overflows, delay updating its parent node.




























CONCLUSION

Making a data structure thread-safe is notoriously difficult in practice.

We focused on B+Trees but the same high-level techniques are applicable to other data structures.

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NEXT CLASS

We are finally going to discuss how to execute some queries...



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